

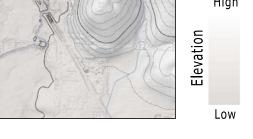


## **Lidar Imagery Series**

Cartography by Jed Roberts and Rudie Watzig, Oregon Department of Geology and Mineral Industries. Additional cartography and data processing by John English, Sarah Robinson, Mathew Tilman, and Kaleena Hughes, Oregon Department of Geology and Mineral Industries.

Data Source: Lidar data from DOGAMI. Lidar flown 2007. Hydrology features digitized from lidar data by DOGAMI. Feature names from Google Maps, U.S. Bureau of Land Management, U.S. Geological Survey, and ESRI. Contours derived from bare earth elevation model smoothed by  $60' \times 60'$  averaging kernel.

Contour interval: 20 feet



The bare earth image is a representation of the earth's surface stripped of man-made objects and vegetation. This is achieved by post-processing lidar point data.

The highest hit image is a representation of the landscape at the time of the lidar flight. Unlike the bare earth image, this image shows features such as trees, buildings, and even cars.

Lidar Data Origins and Map Image Limitations

detection and ranging) technology. A lidar measurement system georeferenced raster grids (ESRI format) interpolated from the point collects huge quantities of three-dimensional point data where laser cloud data. pulses have been reflected off opaque objects such as buildings, trees, bushes, and the ground surface. The map images depicted here are examples by DOGAMI using GIS techniques to extract and emphasize selected features. These map

The lidar all-returns point cloud data that are the original basis for images, the interpretative content displayed, and this lidar image these images were collected by Watershed Sciences Inc., TerraPoint, series are for general information purposes and are not intended to LLC, and Merrick and Company. The point cloud is a remotely sensed indicate the authoritative location or definition of real property collection of three-dimensional point data that are systematically boundaries, the precise shape or contour of the earth, or the precise calibrated relative to GPS ground control points.

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